Distributed Temperature Sensing as a down-hole tool in hydrogeology

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Distributed Temperature Sensing (DTS) technology enables Abstract. 3 down-hole temperature monitoring to study hydrogeological processes at un-4 precedentedly high frequency and spatial resolution. DTS has been widely 5 applied in passive mode in site investigations of groundwater flow, in-well 6 flow, and subsurface thermal property estimation. However, recent years have 7 seen the further development of the use of DTS in an active mode (A-DTS) 8 for which heat sources are deployed. A suite of recent studies using A-DTS 9 down-hole in hydrogeological investigations illustrate the wide range of dif-10 ferent approaches and creativity in designing methodologies. The purpose 11 of this review is to outline and discuss the various applications and limita-12 tions of DTS in down-hole investigations for hydrogeological conditions and 13 aquifer geological properties. To this end, we first review examples where pas-14 sive DTS has been used to study hydrogeology via down-hole applications. 15 Secondly, we discuss and categorize current A-DTS borehole methods into 16 three types. These are thermal advection tests, hybrid cable flow logging, and 17 heat pulse tests. We explore the various options with regards to cable instal-18 lation, heating approach, duration, and spatial extent in order to improve 19 their applicability in a range of settings. These determine the extent to which 20 each method is sensitive to thermal properties, vertical in well flow, or nat-21 ural gradient flow. Our review confirms that the application of DTS has sig-22 nificant advantages over discrete point temperature measurements, partic-23 ularly in deep wells, and highlights the potential for further method devel-24

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- ²⁵ opments in conjunction with other emerging fiber optic based sensors such
- ²⁶ as Distributed Acoustic Sensing.

1. Introduction

Heat is widely recognised as an excellent tracer for a range of hydrogeological processes 27 that can be inferred from temperature-depth measurements in boreholes [e.g., Saar, 2011]. 28 The advantage of using heat over other tracers such as geochemical tracers, is that heat 29 is ubiquitous, and easily and economically measured *in-situ* with a variety of probes 30 and loggers with resolutions down to 10^{-3} °C [Pehme et al., 2013]. Near-surface (upper 31 several m) temperature measurements in either shallow piezometers or by pushing probes 32 into the ground [e.g., Bense and Kooi, 2004; Conant, 2004; Schuetz and Weiler, 2011] 33 can be used to identify and quantify rates of groundwater-surface water interactions by 34 exploiting the effect that groundwater upwelling or downwelling affect the propagation of 35 the seasonal/diurnal temperature wave into the subsurface [Taniguchi, 1993].

At depths greater than ~ 20 meters seasonal surface temperature fluctuations can usu-37 ally no longer be detected. Here the geothermal gradient usually dominates temperature-38 depth profiles which is a function of both the local geothermal heat flux and thermal 39 conductivity of the formation, primarily governed by Fourier's Law of heat conduction. 40 Where a temperature-depth profile departs from this expected behaviour, it is often in-41 dicative of groundwater flow which drives the advection of heat in addition to conduc-42 tion. Temperature-depth profiles can become convex or concave for upward or downward 43 groundwater flow respectively [e.g., Bredehoeft and Papadopulos, 1965] whilst localized 44 horizontal groundwater flow through fractures or faults often results in localised abrupt 45 temperature changes that depart from the geothermal gradient [Ge, 1998; Bense et al., 46 2008]. 47

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The use of Raman-scatter based optical-fibre sensors to infer a spatial distribution of 48 temperature along the fibre hosted in an enclosure (e.g., cable tubing), commonly known 49 as Distributed Temperature Sensing (DTS) has seen a steep rise in popularity in studies of 50 groundwater-surface water interactions [e.g., Selker et al., 2006; Briggs et al., 2012a; Hare 51 et al., 2015 in which it forms an attractive alternative for conventional point temperature 52 measurements. To a lesser extent DTS has been deployed to evaluate hydrogeological 53 conditions at depths below the seasonal zone (e.g., > 20 m), but these can only be accessed 54 via boreholes (up to several km deep) or, in unconsolidated sediments, via direct-push 55 methods (up to ~ 80 m). The latter application will be the focus of this review. 56

This paper focusses on discussing the current state and range of options and techniques involving DTS technology in down-hole settings to investigate groundwater hydrological conditions. After summarising the principles of DTS with special attention to the relationship between resolution in space and time, we review the feasibility and limitations of DTS technology for groundwater studies in down-hole applications.

2. Principles of Distributed Temperature Sensing

DTS uses the Raman backscatter characteristics of light emitted following a laser pulse 62 into a fiber optic cable to determine the distributed temperature along fiber as long as 35 63 km. Raman backscatter is generated by the inelastic interaction of the incident light with 64 molecular vibrations in the fibre that causes the energy level of the emitted photons to be 65 shifted up or down relative to the injected light [Rogers, 1999] (Figure 1). A measurement 66 of the ratio of the intensity of photons returning at specific higher (anti-Stokes) and specific 67 lower wavelengths (Stokes) in time allows for the calculation of the temperature along 68 a fibre allows the computation of temperature as a function of distance [Farahani and 69

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Gogolla, 1999; Hausner et al., 2011]. In most hydrological applications DTS control units 70 are used that determine distance via the transit time of backscattered light by exchanging 71 time for distance, under the same principles as an optical time domain reflectometer 72 (OTDR) [Dakin et al., 1985]. In an alternative implementation, DTS systems can also be 73 based upon optical frequency-domain reflectometry (OFDR) [Bolognini and Hartog, 2013]. 74 Both OTDR and OFDR techniques use the fiber itself as a continuous sensing element 75 that is interrogated over a certain distance of cable. Alternatively, at point locations 76 the fiber Bragg gratings (FBG) may be etched into the fiber which allows to obtain a 77 temperature at point locations [Guan et al., 2013]. To discuss the specifics and potential 78 dis- and advantages of these DTS techniques (OTDR/OFDR-based, or using FBGs), and 79 other possible approaches (e.g., the use of different wavelengths for the emitted light) goes 80 beyond the scope of this review. 81

2.1. Temperature calibration and monitoring modes

After sending out high-frequency laser pulses, a DTS instrument analyses the Stokes 82 and anti-Stokes intensities integrated over user specified time and spatial intervals along 83 the cable. From these data the average temperature for each increment of length along 84 a fiber optic cable is calculated using three calibration parameters. Values for these 85 calibration parameters are typically obtained by use of an instrument-internal reference 86 coil of fiber in combination with internal and external temperature probes attached to the 87 DTS unit. However, light loss (e.g., from fibre damage or where it has been spliced) at any 88 location along the path can result in abrupt offsets in computed temperature along the 89 cable which values easily exceed ± 1 K. Much more accurate temperatures (on the order 90 of 0.02 C) can be obtained through use of external reference temperature baths [Tyler 91

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et al., 2009], and post-processing of the observed Stokes and anti-Stokes data to calculate temperature values [Hausner et al., 2011; Van De Giesen et al., 2012]. These reference baths must create homogeneous temperature conditions, which need to be constant over the measurement integration time, in which lengths of fiber optic cable of for example at least 10-times the sampling interval, and fully external reference temperature loggers are installed [Hausner et al., 2011; Van De Giesen et al., 2012].

Ideally, calibration is based upon at least three externally measured temperatures taken 98 along each section of fiber (i.e., between locations of splices or connectors), two of which 99 must be separated in space. When there are three locations with known temperatures 100 (e.g. water baths in which temperatures are constantly homogenised), but a splice or 101 damage exists at a location in between, it is possible to correct the ratio of the Stokes and 102 anti-Stokes intensities to account for the differential attenuation occurring at this point 103 [Hausner and Kobs, 2016]. The two general configuration options for the optical path 104 of the fiber are known as single-ended and double-ended configurations, and cables may 105 be produced as simplex or duplex (i.e., with either one or two fibers in the same cable) 106 each of which presents specific options for calibration. Generally speaking, duplexed and 107 double-ended operations allow for more accurate calibration since multiple measurements 108 are then taken at each location along the cable. In borehole deployments any of these 109 options may be appropriate and are outlined briefly here. 110

In a conventional single-ended set up, a single fiber is coupled to the base unit and terminated at the other end. This cable can be looped back in and out of a borehole [*Read* et al., 2013] in which case in principle the temperature-depth profile should be symmetrical around the downhole turn-around point. If the loop constructed within a single cable by

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connecting two fibers at the remote end, this would be called a duplexed installation. In 115 either case, the looped set-up and the consequent symmetry of the measurement can be 116 used to depth locate the observed temperatures (Figure 1). Duplexed cables do present 117 certain potential issues. First, the splice at the end of the cable must be protected, which 118 in the case of deep boreholes, can require a high-pressure enclosure. Further, the data 119 after the splice need to be adjusted for potential differential loss of the return signals at 120 the fusion splice [Hausner et al., 2011]. Additionally, such splices can generate spatially 121 distributed defects in temperature measurement, which can be challenging to detect and 122 correct for [Arnon et al., 2014a]. 123

Double-ended installations are those where the optical path of the fiber both begins 124 and ends at the DTS, so that light might be passed both directions along the fiber. 125 Measurements are taken alternately from each instrument channel, which are referred 126 to as the forward and reverse directions [Van De Giesen et al., 2012]. In this way it is 127 possible to compute calibration parameters for each section of the fiber to adjustment 128 for non-uniform differential attenuation along the cable occurring at bends, connectors, 129 splices, and where there has been fiber degradation (e.g., hydrogen ingress). The key 130 point here is that the calibration strategy is dictated by the fiber layout, and must be 131 considered in detail as part of the experimental design. 132

2.2. DTS performance metrics

The key metrics of DTS system performance are the accuracy and precision of reported temperature, at the specified spatial resolution and integration time. The uncertainty in temperature is typically characterized by the standard deviation or Root Mean Square Error (RMSE) of the reported temperature in comparison to the true temperature. The

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RMSE in temperature normally scales with the square root of the product of the inte-137 gration time and the length of cable over which the temperature is being reported. This 138 reflects the central limit theorem applied to the number of photons employed in the inten-139 sity estimates. The RMSE is also a function of distance along the cable due to Beer's Law 140 attenuation of light with travel distance from the base unit, with data further from the 141 instrument having lesser accuracy. The relationship between RMSE and distance is more 142 complicated in the case of double ended measurements, wherein reported temperatures 143 are computed using light travelling in both directions along the cable. For double-ended 144 installations the lowest RMSE occurs at the mid-point of the cable equidistant from the 145 base unit along each channel. 146

DTS units can be set to report back temperatures at a range of sampling intervals, 147 wherein the spatial resolution is always at least twice than this value by the Nyquist 148 theorem [Selker et al., 2014]. The limiting spatial resolution of a DTS is determined at 149 a step change in temperature along a cable, and is defined as the distance between the 150 points for example at 10% and 90% of the true temperature change [Tyler et al., 2009; 151 Selker et al., 2014]. Putting these concepts together lead DTS manufactures to report 152 measurements the less than half of the limiting spatial resolution. Each reported Stokes 153 and anti-Stokes backscatter intensity, and hence the calculated temperature, at a specific 154 distance is an average weighed by a Gaussian function along the sampling interval (Figure 155 2). When discussing temporal resolution we mean it to be the ability to detect temperature 156 change in time. The temporal resolution of an measurement configuration is limited by a 157 combination of the performance of the DTS instrument and thermal inertia of the cable 158 used. In groundwater systems temperatures are only slowly changing naturally at a rate 159

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well within the temporal resolution of any DTS system, however in A-DTS configurations 160 temperatures will be changing at a much higher rate and the temporal resolution of the 161 system used will need to be considered more carefully [e.g. Read et al., 2014]. Modern 162 DTS systems typically can sense temperature distributions along the entire cable every 163 few seconds. Hence, cable thermal properties are commonly the most significant factor in 164 thermal responsiveness. Larger diameter and more massive cables of high thermal inertia 165 respond more slowly to ambient temperature changes. As long as data storage is not a 166 limiting factor, it is usually advisable to set the spatial and temporal averaging to the 167 highest possible frequency the instrument supports, since internal averaging applied by the 168 instrument cannot be subsequently undone. Typically post-processing averaging provides 169 all the advantages which would be obtained from longer collection intervals. This should 170 be confirmed for each DTS base unit as we know of one manufacturer employs methods 171 that violate this assumption wherein there is a penalty to selecting high temporal and 172 spatial resolution. In all cases data collected at high frequency can lead to unwieldily 173 data sets (e.g., from a long cables and long-duration installations). Furthermore, on some 174 instruments data can be recorded faster on the instrument than it can be downloaded, 175 resulting in the memory limit of the instrument eventually being reached. 176

2.3. Cable selection and installation

In shallow wells it is typically possible to install a fibre-optic cable by spooling it off into the well to the desired maximum depth and left to monitor temperature. In deeper wells the feeding of the cable into the entrance of the well may need to be addressed to support the weight of the cable and limit bending radii. Fiber optic cables must be protected from damage due impact from pumps or co-located instruments. In deep wells fiber optic

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cables are often installed in the cement behind the borehole casing where they are nonreplaceable. So-called pump down systems are commonly used in oil and gas applications [*Smolen and van der Spek*, 2003], but not so in hydrogeology. These use a small diameter open tube sitting inside the borehole in which a fibre-optic cable can be led down and replaced if necessary after deterioration of the fibre over time for example after prolonged exposure to high temperatures in a geothermal heat production or oil well.

Short-range DTS units (under 10 km) generally use multi-mode fibers (typically 50 μ m 188 core diameter, 125 μ m cladding diameter). The added glass cross-section allows injection 189 of greater light intensity, and captures a larger fraction of the backscatter compared 190 to single-mode fibers, which results in higher measurement performance. Cable design 191 that includes multiple fibers are advisable for down-hole applications as these provide 192 redundancy in case of damage occurring to one, and allows single-ended or double ended 193 measurements to be obtained by fusion splicing two fibers together at the far end of the 194 cable (Figure 1). 195

Every fusion splice needs physical protection. Above ground splice protection is pri-196 marily against movement of the fiber and exposure to water. Downhole splices must 197 be protected against pressure using specially designed enclosures, sometimes potting the 198 splices in rigid resin. The entire fiber must be protected pressure which can cause non-199 uniform differential attenuation. Fibers are often hermetically sealed into rigid (plastic 200 or stainless steel, depending on required pressure rating) capillary tubes. Since the fiber 201 must be completely protected from mechanical stress, the fibers path within the capillaries 202 is helical to accommodate slight changes in the cable length if it is put under tension or 203 experiences significant temperature changes. This results in an optical path that is about 204

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0.5 percent longer than the cable. For sites that may contain organic compounds the 205 cable design should include hydrogen-scavenging gel. Further protection from hydrogen 206 ingression is obtained by encasing the stainless steel capillary tube in aluminum, which 207 has much lower gas permeability [Reinsch et al., 2013]. Additional crush resistant armor-208 ing, tensile elements, and abrasion resistant plastic jacket may be needed. Selection of 209 jacket material also must accommodate any markings needed, such as distance increments. 210 In down-hole applications, cables require sufficient tensile strength to support their own 211 weight over the depth of the deployment without transferring stress to the fiber. 212

In borehole installations it is generally advantageous to seek the highest spatial resolu-213 tion possible. This will enhance the prospect to resolve individually, for instance, closely 214 spaced fractures that carry groundwater flow. As stated above, for most DTS systems, 215 should lower spatial resolution be found to be sufficient, the data may be averaged in 216 post-processing with no loss in performance relative to having obtained the data at lower 217 spatial resolution from the outset. Averaging of high spatial resolution data may be ap-218 propriate when carrying out heat pulse tests in settings where the geology is known to 219 be relatively homogeneous of large depth intervals. In fractured aquifers, where fracture 220 flow may cause localized cooling, averaging high spatial frequency data into a lower spa-221 tial frequency composite may completely average out this response. One may achieve a 222 desired spatial resolution either by selecting an instrument with the desired spatial res-223 olution, or, a wrapped cable can be deployed [Hilgersom et al., 2016]. In such a cable, 224 the optical fiber is wrapped around a central strength member, such that for every unit 225 length of cable there is a greater length of optical fiber, so the effective spatial resolution 226 is increased. Custom made solutions have been used to measure shallow temperatures 227

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with depth in glaciers and lakes [Selker et al., 2006], and stream bed sediments [Briqqs 228 et al., 2012b; Vogt et al., 2010], while pre-wrapped cables can also can be purchased and 229 have been deployed in lakes [Arnon et al., 2014a], and boreholes [Banks et al., 2014]. Data 230 from wrapped cables needs careful processing. In the case of tightly wrapped fibers, there 231 have been documented entrance effects in approximately the first 100 m of fiber after the 232 transition from a straight cable to wrapped cable that if not corrected for, will result in 233 erroneous data [Arnon et al., 2014a]. Because of the distance and time varying nature 234 of the correction, Arnon et al. [2014b] developed an empirically based method for the 235 processing of wrapped cable data. 236

To illustrate the various spatial averaging options, it is useful to look in detail at a 237 short 3 m section of a borehole at the Ploemeur research site, France, using different 238 combinations of instruments and cables (Figure 2). Data were collected by instruments 239 with manufacturer specified spatial resolutions of 2.0 and 0.3 m (sampling at 1.01 and 240 0.12 m respectively) on standard (Figure 2 panels b and c), and wrapped cables (Brugg 241 High Resolution cable, Brugg, Switzerland, Figure 2 panels d and e). An open fracture 242 was encountered at a depth of 23.8 m depth, providing an outflow for groundwater which 243 flowed up the borehole. In such scenario a change of the thermal gradient at the location 244 of the fracture would be expected which could be used to infer the rate of inflow at the 245 location of the fracture [Klepikova et al., 2014]. However, in this example the impact 246 on the temperature gradient of this outflow is very subtle, but detectable, as is apparent 247 from the point temperature measurements shown in Figure 2a. Data from the 2 m spatial 248 resolution instrument and straight cable would give the impression of a relatively smooth 249 temperature depth profile and is unable to detect the change in gradient. In this case, 250

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the 2 m Gaussian spatial weighting of each temperature measurement spans the cased, 251 rock, and fractured rock intervals, rendering these features indistinguishable. In contrast, 252 the 0.3 m spatial resolution instrument with the straight cable (Figure 2c) allows identi-253 fication of the location and quantification of the step temperature change at the fissure, 254 and would provide an improved characterization of the change in gradient over the point 255 measurements (Figure 2a). Wrapping the cable to enhance the spatial resolution in com-256 bination with either low-res or high-res DTS instrument (2d and e) does not seem to result 257 in a detection of the changing gradient at the location of the fracture. This is probably 258 because as a result of the wrapping greater noise is introduced in the data due to the 259 Beer's law light loss along the additional optical path length, and further from light loss 260 that occurs at bends. The effective spatial averaging in Figure 2d) is similar to Figure 2c), 261 but for the latter reason, the temperature resolution is lower. Pairing the 0.3 m spatial 262 resolution instrument with the wrapped cable gives an effective spatial resolution of 0.03 263 m, which is now comparable to the spatial extent of the fractures but still the change 264 in temperature gradient is hardly visible at the location of the fracture (at a depth of 265 23.8 m). Concluding, in this installation only one DTS configuration was successful in 266 detecting the fracture flow process of central interest in this study. This example shows 267 the care required to effectively employ DTS. It is often advisable to pre-test the design of 268 the field installation, choice of DTS, and cable configuration. 269

3. DTS monitoring in Passive mode

DTS measurements are termed "passive" if there is no active heating of the cable itself or in the DTS monitored well. In piezometers or cased boreholes, it can sometimes be assumed that the temperature measured in the fluid at a given depth is the same as the

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temperature in the formation. In open or long screened boreholes, this is often not the 273 case. The inflow of water with different temperature to the resident water causes small 274 inflections in the temperature-depth profile and is useful to identify hydraulically active 275 fractures [Drury et al., 1984]. For large inflows of distinctly different temperature, or in 276 the case of warmer water entering below cooler water, the temperature signal may advect 277 through the well. This temperature signal may allow the flow to be estimated using 278 analytical [Drury et al., 1984], or numerical modeling approaches [Klepikova et al., 2011]. 279 DTS has been used to measure temperature-depth profiles in the subsurface in a variety 280 of settings. Grosswig et al. [1996] monitored seasonal temperature changes in the subsur-281 face at a waste disposal site. They also detected a warm temperature signal just beneath 282 the zone of seasonal fluctuation, attributed to exothermic reactions in surrounding waste 283 material. DTS has also been used to assess lithological changes from passive temperature 284 data in boreholes assuming that changes in temperature gradient reflect variations in ther-285 mal properties coupled to lithology [Foerster et al., 1997; Wisian et al., 1998]. Foerster 286 et al. [1997], concluded that DTS was suitable for studies of terrestrial heat flow, but 287 had a temperature resolution 5 to 10 times less than their conventional logging approach. 288 However, we note that current instruments would be able to significantly improve on the 289 latter result. Henninges et al. [2005] used a similar approach to Foerster et al. [1997] 290 and Wisian et al. [1998] in an area of permafrost, and quantified thermal properties with 291 depth by assuming assuming a uniform vertical heat flow density. The distinct advantage 292 of using DTS in this setting is that the cable can be installed immediately after drilling or 293 incorporated into the well construction [Henninges et al., 2003], when re-freezing of the 294

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²⁹⁵ hole would prevent access to logging devices [*Hurtig et al.*, 1996]. Stotler et al. [2011] also
²⁹⁶ make use of DTS to monitor permafrost and sub-permafrost temperature conditions.

There has been renewed interest in carrying out thermal tracer tests, with passive 297 temperature monitoring in a number of observation wells [Wagner et al., 2014]. This may 298 be stimulated by the desire to directly study heat transport in the subsurface, or to use 299 temperature as an easily monitored tracer for groundwater flow. The advantage of using 300 DTS here is that multiple observation wells can be monitored simultaneously using the 301 same instrument, either by using multiple cables attached to the same instrument, or by 302 using one continuous cable that is looped inside each borehole [e.g. Read et al., 2013]. 303 Thermal tracer tests monitored using DTS have been carried out in a variety of settings 304 including: a sedimentary aquifer [Macfarlane et al., 2002]; a fractured sandstone [Hawkins 305 and Becker, 2012]; a fractured granite [Read et al., 2013]; and a shallow sedimentary 306 aquifer [Hermans et al., 2015]. Recently, Bakker et al. [2015] carried out a thermal tracer 307 test monitored with DTS without monitoring wells using fiber optic cable in the subsurface 308 installed by direct push. In unconsolidated sediments, this approach allows thermal tracer 309 tests to be monitored economically, in detail, and with minimal disturbance to the aquifer. 310

4. DTS monitoring in Active mode (A-DTS)

In A-DTS, the cable [e.g. *Read et al.*, 2014; *Coleman et al.*, 2015; *Hausner et al.*, 2015], borehole fluid [e.g. *Leaf et al.*, 2012; *Read et al.*, 2015], or surrounding rock formation is heated [*Bakker et al.*, 2015]. The temperature response at some or all points during this process is then indicative of either the lithology, ambient groundwater flow, or in well flow, and depends closely on how the cable is deployed in the borehole and the nature of the thermal disturbance. These issues are the subject of this section. We have

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categorized the various current A-DTS methods in Figure 3. These are thermal advection 317 tests (Figure 3a), hybrid cable flow logging (Figure 3b), and heat pulse tests (Figure 3c). 318 Figure 3 shows typical cable set-ups, heating locations, and data, for a well intersecting 319 two fractures with additional layered heterogeneity. We assume that in this well ambient 320 flow (fracture flow freely entering the uncased borehole) or pumping occurs (Figure 3a and 321 b). Alternatively, there exists fracture flow in the formation but this flow is not entering 322 the well (but flowing around it) due to the presence of a casing or by use of a liner (Figure 323 3c). Each of these three principal methods is outlined in turn in the following sections. 324 There are two principal strategies that have been trialled in hydrogeology to intro-325 ducing a thermal anomaly along the DTS cable in the subsurface to enable an A-DTS 326 measurement. These are the physical injection of a fluid (usually water) with a contrasting 327 temperature into the system, or the use of electrical heating techniques. In oil and gas ap-328 plications chemical pills have been used to create thermal anomalies in boreholes [Edwards 329 et al., 2010 which is a method that has not been used in hydrogeological applications as 330

³³¹ far as we are aware.

Injection of fluid with a contrasting temperature may be carried out at a single location 332 and for a short period of time to create a discrete plume in the borehole [Leaf et al., 333 2012. Alternatively, the injection may be carried out over a longer period to replace the 334 fluid in a longer section of the borehole with fluid warmer or colder than the surrounding 335 rock [Yamano and Goto, 2005; Read et al., 2013]. A second way to to create a thermal 336 anomaly is to use electrical conductors within the DTS cable used for measurements to 337 create a heating circuit, a separate heating cable or heating elements. Electrical heating 338 techniques offer several advantages over injecting a fluid. The use of electrical heating 339

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does not disturb ambient vertical flows of which there is a great risk during fluid injection into the borehole as described above. Electrical techniques make it also easier to quantify the amount of heat added to the system that can be readily calculated by integrating the input power over time.

Electrical heating can be carried out along the entire or part of the length of the borehole 344 or at point locations. Point heating can be achieved using small heating elements [Sellwood 345 et al., 2015a; Read et al., 2015]. Uniform heating over lengths of borehole can be achieved 346 with Joule heating along an electrical conductor [Kurth et al., 2013]. It is possible to 347 directly heat the same cable used for DTS temperature monitoring by driving electrical 348 currents through metallic armouring provided that an electrical connection is available to 349 both ends of the cable [e.g., Sayde et al., 2015; Read et al., 2014], utilizing a composite 350 cable design that incorporates parallel electrical conductors and optical fibers [Coleman 351 et al., 2015], or by ad-hoc solutions that involve the manual wrapping of a passive DTS 352 cable around a line source of heat [Liu et al., 2013; Seibertz et al., 2016]. Specifically 353 designed and manufactured cables are typically required since standard cable jackets may 354 not be designed to be safe at elevated voltage. Electrically insulated heating elements 355 inside the same cable construction can be more economical, however, the geometry is not 356 radially symmetric, and small differences in the separation between the heating element 357 and optical fibers may cause temperature anomalies observable during heating. Even 358 with a radially symmetric cable, there may still be longitudinal differences in heating 359 [*Cao et al.*, 2015]. For heated cable methods, the power output from the heated cable, 360 P [W] can be calculated according to P = VI, in which V is the voltage drop along the 361 cable [V], and I [A] is the electrical current. If constant power output through time is 362

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required, an active power controller is needed to supply constant total power (due to the 363 temperature dependent resistance of conductors). The total power output can then be 364 divided by the length of the heated section to obtain the heat generated per meter of 365 cable. In down-hole applications, power inputs in the order of 5-20 W/m have been used 366 successfully. However, the power input to be applied in any specific A-DTS application 367 to generate the most informative dataset would vary with parameters such as borehole 368 radius, potential for generating thermal convection inside the borehole, and the temporal 369 and spatial resolution of the DTS measurement configuration. 370

Since with A-DTS experiments a thermal anomaly (positive or negative) is introduced 371 into the system, there is the possibility that water viscosity and density will be affected to 372 the degree that convection is induced in the system. When this occurs such effects will need 373 to be included in the interpretative framework of the A-DTS dataset. However, relatively 374 simple calculations, for example using Rayleigh number analysis, can give already an 375 indication of how important convection might be in a given system [*Read et al.*, 2015]. 376 Hence, an A-DTS configuration might be designed to minimize the complications arising 377 from such effects. 378

4.1. Thermal Advection Tests

Thermal Advection Tests have been deployed to determine the location and significance of inflows and outflows from wells. In general, the principle is that the introduction of water with an anomalous temperature is tracked as it moves vertically in the well (Figure 382 3a).

The most common form of this method uses a point source to generate a heat pulse. In point heating experiments, the movement of a packet of either warmer or cooler water

in the well bore is tracked using DTS. If dispersion can reasonably be assumed to be 385 symmetrical, then the movement of the temperature peak (or minimum) will be represen-386 tative of the cross-sectionally averaged velocity. The test is carried out with a fiber optic 387 cable installed in the borehole fluid. The point heating approach is possible with either 388 the injection of fluid [Leaf et al., 2012], or with point electrical heating [Sellwood et al., 389 2015a, b; Read et al., 2015]. For fluid injection, a thermally insulated hose is lowered down 390 to the depth of interest and fluid pumped or allowed to drain in from the surface. Point 391 electrical heating makes use of a submersible electric heater lowered down to the target 392 depth. The aim of both approaches is then to create a short section of the borehole with 393 anomalous temperature water that can then be tracked with DTS. Qualitative analysis 394 of the DTS data obtained allow the local flow characteristics to be inferred, for example, 395 the identification of vertical flow and the flow direction. Quantitative analysis involves 396 calculation of vertical flow rates from the displacement of plume peaks between successive 397 DTS temperature profiles. 398

Figure 4 shows a point heating experiment carried out in a borehole penetrating a 399 sparsely fractured aquifer, adapted from [Read et al., 2015], where it is referred to as 400 the Thermal-Plume fiber Optic Tracking (T-POT) method. Here a point heater, at a 401 depth of 68 m, generated a localized region of warmer water. Heating was switched 402 off, and pumping at shallow depth simultaneously began, advecting the plume upwards. 403 Assuming no significant heat loss from the bore to the formation, tracking the plume 404 peak allowed the upward fluid velocity in the borehole to be calculated at 11.3 cm s⁻¹. 405 Through a series of controlled tests, Sellwood et al. [2015b] showed that thermal advection 406 tests can be used to measure velocities down to below 0.06 cm s^{-1} . If the vertical flux to 407

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⁴⁰⁸ be measured is high, then injecting fluid may be acceptable. However, if attempting to ⁴⁰⁹ measure very low velocities, then fluid injections are likely to disturb the hydraulic head ⁴¹⁰ in the well and therefore the velocity itself. In such conditions, point electrical heating ⁴¹¹ would be preferable. In an oil and gas reservoir setting *Rahman et al.* [2011] have carried ⁴¹² out similar point heating experiments in well bores.

A variant of this method is to heat or inject at a point continuously. The result is a front of warm or cold water that propagates vertically through the well. This has been applied mainly in deep [Yamano and Goto, 2005], and geothermal wells [Ikeda et al., 2000; Sakaguchi and Matsushima, 2000]. In such tests, the spacing of the front as it vertically propagates can be used to locate inflows and outflows. Additionally, the analytical solution presented by Yamano and Goto [2005] allows the temperature depth profile, following prolonged injection of water at the surface, to be inverted for flow.

A third variant is to use a distributed, rather than point heat source. This was carried 420 out by [Banks et al., 2014] using a heating cable and a wrapped high spatial resolution 421 fiber optic cable separated by a fixed distance. Figure 5 shows DTS temperature data 422 obtained prior to heating, during heating, and then after pumping was initiated at the 423 top of the borehole. Once pumping was started, the inflowing fractures caused step-like 424 reductions in fluid temperature. As suggested by *Banks et al.* [2014], it may be possible 425 to derive a flow log based on the gradients of the temperature depth profile between 426 fractures, and the size of the temperature reductions. While this method is not as simple 427 as the point method for velocity estimation, it has the advantage that the entire borehole 428 can be evaluated simultaneously. 429

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4.2. Hybrid cable flow logging

In-well vertical flow may also be monitored with hybrid cable flow logging. In this method, heating occurs within the same cable as the optical fibers, and the cable is deployed in a well in contact with flowing groundwater (Figure 3b). The principle is that when the cable is heated with a constant power input over time, the temperature inside the cable at steady state is a function of the velocity of the surrounding water. Higher velocities reduce the cable temperature by more effectively thinning the thermal boundary layer in the fluid around the cable. This method has also been used to estimate wind speeds [Sayde et al., 2015] and seepage through dams [Aufleger et al., 2007]. Read et al. [2014] show that for a typical armored cable with radial symmetry, the temperature difference between the cable centre and water temperature ΔT is given by:

$$\Delta T = \frac{Q}{2\pi} \left(\frac{1}{hr_2} + \frac{1}{k_c} \ln \frac{r_2}{r_1} \right) \tag{1}$$

where Q [W m⁻¹], is the heat input to the cable, h [W m⁻² K⁻¹], is the heat transfer coefficient, r_1 is the radius of the armoring, r_2 is the total cable radius, and k_c [W m⁻¹ K⁻¹], is the thermal conductivity of the insulating material between r_1 and r_2 . In practice, it is difficult to calculate h from first principles, however it can be readily found empirically by taking measurements at a number of known flow velocities during a field test [e.g. *Read et al.*, 2014], or could be inferred from controlled lab experiments.

Figure 6 shows values of ΔT collected in a pumped well from the dataset collected by *Read et al.* [2014], with a velocity profile obtained with an impeller flowmeter for comparison. The hybrid cable method identified step changes in flow from inflowing fractures that appeared as step reductions in the ΔT . The hybrid cable log also suffered from some artifacts due to cable deployment. Where the cable touched the wall, at around

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⁴⁴¹ 60 m depth, the ΔT value was higher. The presence of other objects inside the well, in this ⁴⁴² case 2 m spaced plastic centralizers to keep the heated cable in the center of the borehole, ⁴⁴³ caused localized cooling thought to be due to the stimulation of vortices enhancing the ⁴⁴⁴ heat transfer.

The hybrid cable approach has the advantage that it is possible to monitor time varying velocity and flow changes more readily than with point thermal advection tests. However, since the response is sensitive to anything altering the efficiency of heat transfer from the cable, effects due to varying cable centralization or other instrumentation in the well disturbing the flow may be apparent. It is also likely to require empirical calibration in the field and each well prior to use.

4.3. Heat pulse tests

⁴⁵¹ Apparent thermal properties along a wellbore can be characterized using DTS heat ⁴⁵² pulse tests. This method is based on applying a constant power output over the entire ⁴⁵³ deployed cable length for a period of time and monitoring the heating and/or cooling ⁴⁵⁴ phases using DTS [*Coleman et al.*, 2015; *Hausner et al.*, 2015; *Seibertz et al.*, 2016]. The ⁴⁵⁵ measured thermal response is dependent on both conductive and advective components of ⁴⁵⁶ heat transfer. Through careful analysis information regarding both lithological variations ⁴⁵⁷ and natural gradient flow distributions can be gathered.

In heat pulse tests, heating or cooling data may be used. An analytical solution exists for constant heat injection in a homogeneous, radially symmetric porous medium. This is given by [Shen and Beck, 1986]:

$$k_a = \frac{Q}{4\pi} \cdot \frac{\ln(t_2/t_1)}{T_2 - T_1} \tag{2}$$

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where k_a [W m⁻¹ K⁻¹] is the apparent thermal conductivity of the formation, Q [W 458 m^{-1}] is again electrical power input, and T_1 and T_2 are the temperatures at times t_1 and 459 t_2 respectively. Heat Pulse Tests can be conducted using either separate heating and fiber 460 optic cables or with a composite cable that incorporates both resistance heating wires 461 and optical fibers. Early installations [e.g., Freifeld et al., 2008], utilized separate cables 462 for heating and temperature measurements in which the distance between these cables 463 is variable with depth. Temperature measurements during heating are highly dependent 464 on the distance between the heating wires and optical fibers; thus, cooling data were 465 exclusively used for data analysis where distance variations had much less of an effect. 466 The application of composite cables has allowed for both heating and cooling data to 467 be analyzed [Coleman et al., 2015; Hausner et al., 2015]; however, cable materials and 468 geometry as well as installation geometry still play a major role in the measured response 469 and is an area of ongoing research. For example, variable cable coupling between the rock 470 formation and wellbore fluids can negatively impact the measurement response. Care 471 must be taken when applying equation 2 for composite cables. The initial temperature 472 increase will be due to the thermal properties of the cable, so late time data must be 473 used. Detailed numerical modelling can be used to assess in more details the relevance 474 of these various complicating factors for the interpretation of A-DTS data sets [Hausner 475 et al., 2015]. 476

Since heat pulse tests measure apparent thermal properties, specific information regarding the field installation is required if isolating the conductive and advective components of heat transfer is desired. *Freifeld et al.* [2008] deployed cable inside a 535 m deep borehole through volcanic strata in a permafrost environment, and used a 1-D radial model to

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invert cooling data from a heat pulse test to determine a thermal conductivity profile. In 481 this case both natural gradient flow and vertical wellbore flow variations were assumed to 482 be negligible in order to calculate thermal conductivity profiles. If the thermal properties 483 of the rock strata are known there is significant potential for using apparent thermal data 484 to quantify flow [Coleman et al., 2015]. Figure 7 highlights the modeled effect of flow 485 on Heat Pulse temperature data in comparison with field data collected in a dolostone 486 aquifer. Differentiating natural gradient groundwater flow from lithological variations re-487 mains challenging. To determine lithological changes, groundwater flow must be known 488 or assumed; whereas, to isolate groundwater flow thermal properties of the rock must 489 be known a priori. In either case the borehole should be cased or sealed using a flexi-490 ble borehole liner to eliminate cross-connected wellbore flow that would cause significant 491 measurement bias. 492

5. Future Developments

Both the hybrid cable and heat pulse methods are at a relatively early stage of devel-493 opment in hydrogeological applications. Whilst in oil and gas studies similar methods 494 are already more widely applied [Bolognini and Hartog, 2013] they are mostly used as 495 qualitative monitoring solutions. The main development to be looking forward to is to 496 make down-hole DTS methods into tools from which quantitative data can be gathered 497 on hydrogeological conditions outside the borehole. Numerical modeling can be expected 498 to be an important route in this process as they can consider the complex geometries as-499 sociated with borehole installations and its impact on the strongly coupled fluid and heat 500 flow processes associated with (A-)DTS experiments. Such simulations should be used to 501 assess and quantitatively interpret DTS data sets for hydrogeologically relevant param-502

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eters (e.g. formation groundwater flow). Moreover, prior to field installations they can serve to trial the large range of options for deployment (e.g., configuration of the cable in the system, optimum A-DTS heat input) that many current researchers are so creatively exploring. This is critical since, as we have shown in this review, all of the choices associated with the design of a down-hole DTS deployment will impact the effectiveness of DTS in obtaining valid and valuable data.

While there are many literature examples of subsurface DTS application, there is plenty 509 of opportunity for future development of the technology in groundwater studies as instru-510 ment and cable performance improve. Further work is also needed to assess the sensitivity 511 of active methods under different conditions to both in well vertical flow and natural gra-512 dient flow, and turn them into readily deployable monitoring solutions providing quanti-513 tative results. In order to do this auxiliary data are needed to complement DTS data sets. 514 Spatially distributed data like DTS are likely to originate from other hydrogeophysical 515 methods which are still actively developed [Binley et al., 2015]. DTS can be combined 516 with such methods like it is with, for example, with Distributed Acoustic Sensing which 517 is another optical-fibre sensing method [Noni et al., 2011; Mondanos et al., 2015]. 518

6. Conclusion

⁵¹⁹ Our overview has highlighted examples where DTS has been used in studies of aquifer ⁵²⁰ heterogeneity, groundwater flow, subsurface heat transport, and geothermal and CO₂ ⁵²¹ sequestration. Such deployments are typically either passive or active. In passive applica-⁵²² tions, DTS can provide near real time temperature monitoring, simultaneously, potentially ⁵²³ in multiple deep wells at high spatial resolution. This allows dynamic processes to be mon-⁵²⁴ itored in detail, and long data sets to be efficiently collected. Active DTS methods aim

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to primarily measure in-well flow (thermal advection tests and hybrid cable flow mea-525 surements), and thermal properties and natural gradient groundwater flow (heat pulse 526 tests). While there are some similarities between the active methods, it is important to 527 note the differences in the sensitivities of each method and the underlying physics. When 528 considering undertaking field or laboratory experiments active and passive methods may 529 easily be combined to efficiently obtain different but complementary data. For instance, 530 after heating a cable for a long duration, it may be possible after hybrid cable flow logging 531 to monitor the return of the slightly warmed borehole to background temperature. The 532 first measurements would give flow in the well, while the second may yield information 533 on aquifer heterogeneity and thermal properties. 534

When to use DTS in a borehole setting requires careful consideration. If there is a 535 passive process to be monitored with either little time or depth variability, then a log 536 obtained with a high temperature resolution temperature probe, or a time series from 537 a data logger at a particular depth might yield equivalent or better datasets with less 538 effort. However, DTS is proving invaluable in applications where there is significant time 539 and depth variability. Here, the required effort in terms of installation of power supply, 540 calibration baths, and the post-processing of the data should far be outweighed by the 541 benefits to hydrogeological research provided by the wealth of additional detail in spatio-542 temporal temperature dynamics recorded by DTS. 543

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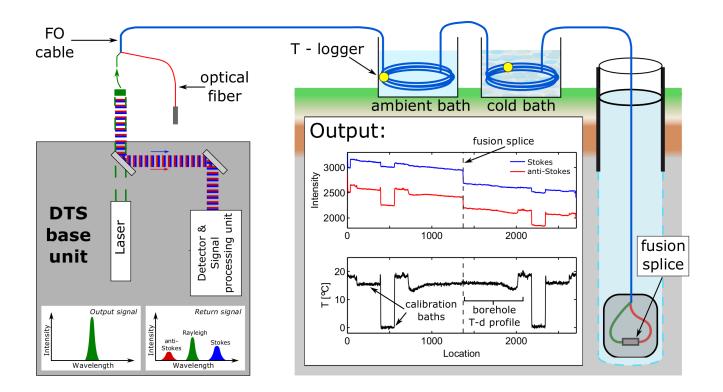


Figure 1. Schematic of DTS principles based upon Raman backscatter detection. In this cartoon a fibre-optic cable is deployed in a duplexed single-ended set up. A double-ended measurement would be possible by additionally connecting the red optical fiber to the instrument, and alternating measurements between the two instrument channels

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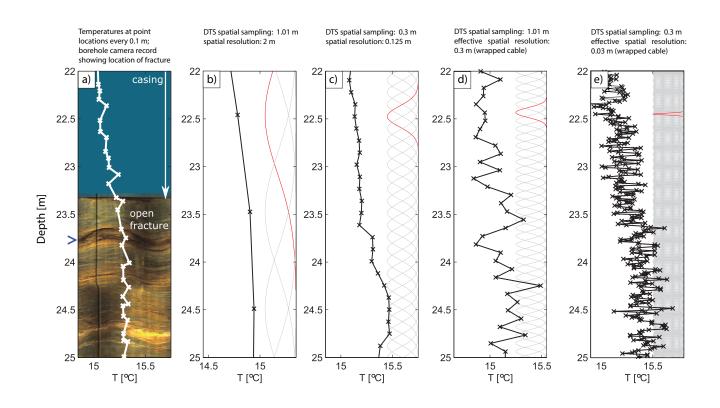


Figure 2. Section of a temperature-depth profile collected in an open well at the Ploemeur research site, France, showing a) optical televiewer and temperature depth-profile measured with a high precision temperature probe measuring every 0.1 m, b) 2 m spatial resolution (1 m spatial sampling) instrument with a standard cable, c) 0.3 m spatial resolution (0.125 m spatial sampling) instrument with a standard cable, d) 2 m spatial resolution (1 m spatial sampling) instrument with a standard cable, d) 2 m spatial resolution (1 m spatial sampling) instrument and wrapped cable, and e) 0.3 m spatial resolution (0.125 m spatial sampling) instrument and wrapped cable. Each DTS temperature-depth profile is a 10 minute time average collected on the same day. Grey curves (one highlighted in red) show the Gaussian spatial weighting function for each DTS-reported temperature measurement along the cable (marked with x's in the plots), calculated using the method given in *Selker et al.* [2014]

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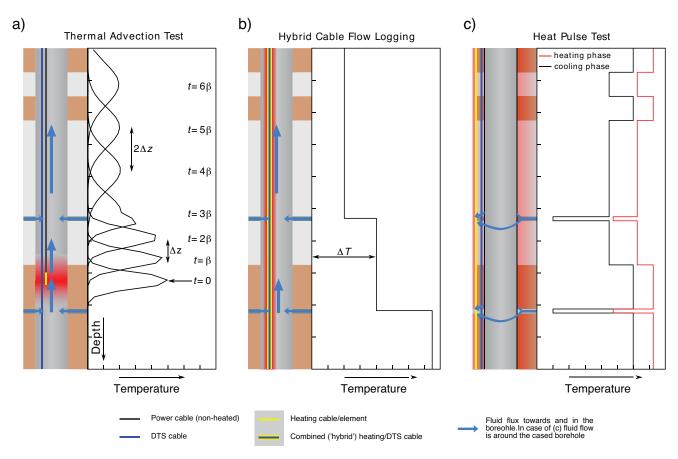


Figure 3. Schematic of three Active-DTS methods in a well intersecting two discrete transmissive zones (e.g. fractured intervals) and varying lithology. Right-hand side panels in (a-c) show the diagnostic data to be observed for each test. a) Thermal Advection Test with temperature depth profiles after point injection or point heating resulting in a quantification of flow in the borehole driven by inflow from discrete fractures, b) Hybrid Cable Flowmetry in which in-well flow is quantified, and c) a Heat Pulse Test with temperature data from the heating and cooling phase as observed outside the borehole either by using a liner [e.g. *Leaf et al.*, 2012] or by installation of DTS cables in a borehole casing grout, or via direct-push techniques (not shown) in the absence of a borehole [*Bakker et al.*, 2015]. Heating- and cooling data can be used to infer apparent thermal properties of the formation that can be related to both heat-advection (groundwater flow) and heat-conduction in the formation. See the text on each method for further detail.

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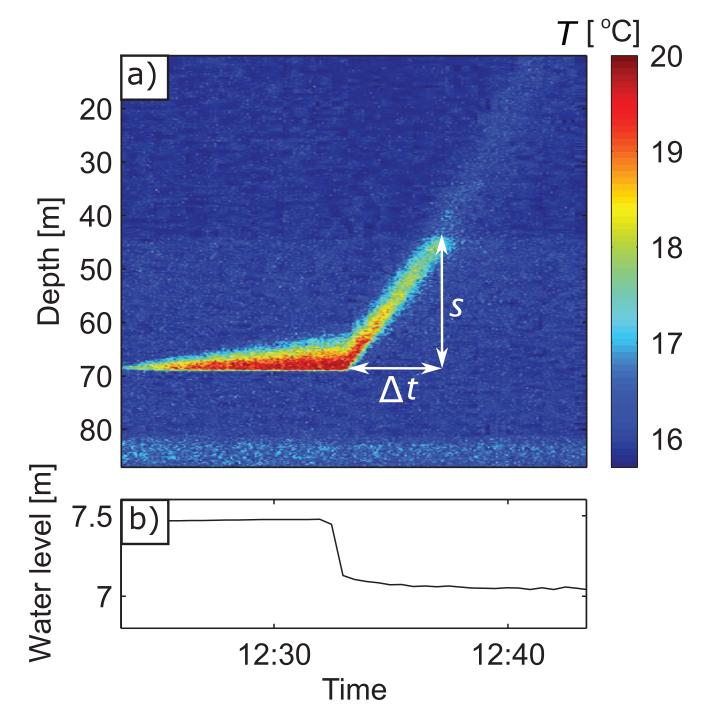


Figure 4. Electrical point heating experiment carried out in a well with ambient vertical flow, then stimulated by pumping (adapted from *Read et al.* [2015]), showing a) DTS measured temperature showing the distance (s) travelled (upward in this case) by the thermal anomaly introduced at the point heating element within a certain time interval (Δt). The water velocity in the well is given by $s/\Delta t$. b) The water level in the well during the test. Pumping was initiated $P_{tt} P_{12} A_{3} F T$ October 31, 2016, 11:05am D R A F T

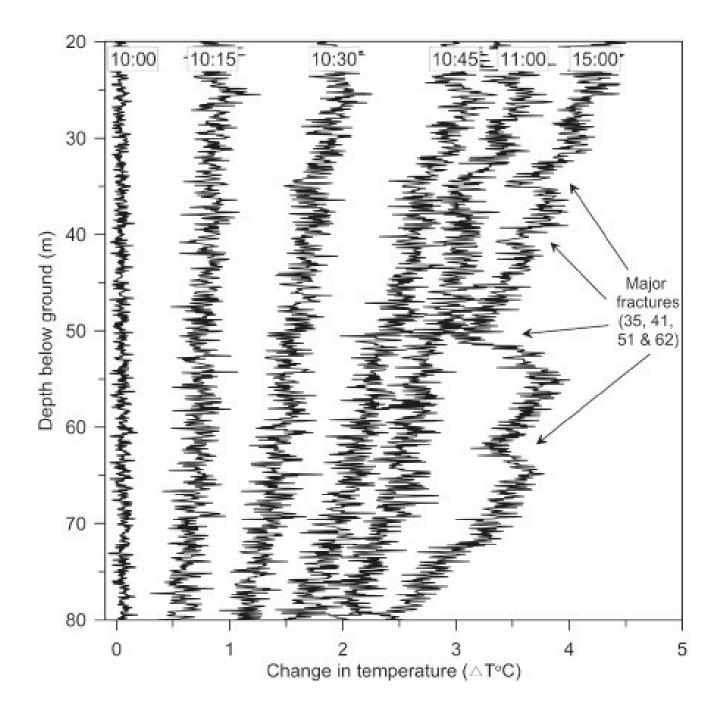


Figure 5. Schematic response after heating an open borehole with separate heating cable in both ambient conditions and then during pumping, taken from *Banks et al.* [2014]

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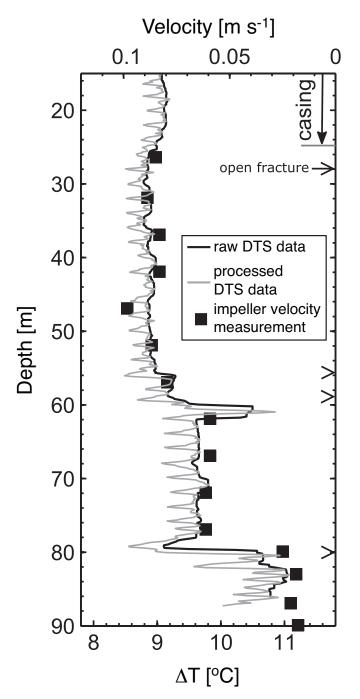


Figure 6. Comparison of ΔT profile and velocity point measurements with an impeller flowmeter during a pumping test, adapted from *Read et al.* [2014]. The 'processed' ΔT profile is the result of a moving median filter applied to the original data in order remove the local effect of the cable centralizers used in the deployment

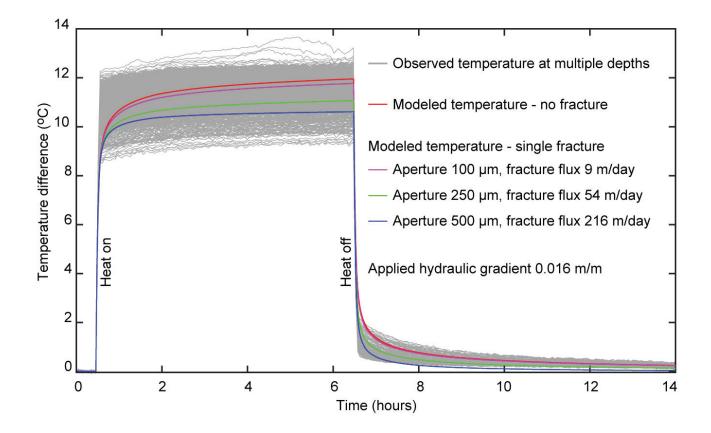


Figure 7. Field data from a borehole heat pulse test in a borehole with strongly varying groundwater influxes [*Coleman et al.*, 2015]. Field data show a wide range of responses and models have been used to provide an initial indication over which range the these fluxes would vary to understand the observed variability is DTS measured responses and hence the sensitivity of the measurements to the groundwater influx.

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